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Near Real Time Evapotranspiration Estimation Using Remote Sensing Data

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Background

Measurement of evapotranspiration (ET) is important to water management as irrigation is by far the largest consumptive use of water, both globally and in the western U.S. Nonetheless, most water management models are based on water allocations, and not on actual (measured) water use, in part because direct observations of irrigation water use are difficult to obtain. For instance, traditional methods of estimating ET typically provide potential or reference ET at points, rather than spatial information about actual ET,

Satellite remote sensing is a promising tool for estimating the spatial distribution of ET at regional (and larger) scales. Different methods have been developed to use satellite remote sensing data in surface flux estimation schemes. However, most existing schemes for ET estimation require ground observations that may be difficult to obtain at large scales. There remain open questions as to the ability of satellite remote sensing to provide large area ET estimates independent of ground observations.

Objective

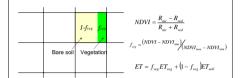
The objective of this study is to map the spatial distribution of near real time ET over large areas using remote sensing data (without in situ data) and to evaluate the potential for use of the standard MODIS ET algorithm (Nishida, K., et al., 2003) for possible use to estimate agricultural water use in real-time for irrigated areas.



•Critical model input and parameters must be available in near real-time (~1 day lag). •The algorithm must be robust. ET estimations are constrained by energy and mass conservation and have relatively lower sensitivity to input data errors.

 The algorithm must be insensitive to constraints imposed by the twice-daily overpass of the satellite and cloud screening.

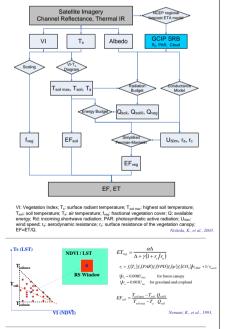
Methodology Linear Two-Source Model (from Nishida et al, 2003) •The landscape is simplified as a mixture of vegetation and bare soil. •The proportion of vegetation, f_{yyz} whose value is between 0 and 1, is related to normalized difference vegetation index (NDVI).



Algorithm - our implementation

•A combination of vegetation index and surface temperature (T. known as the VI-T_o diagram method, is used.

•Evaporation Fraction (EF) is estimated using remote sensing data and scaled to get daily ET.



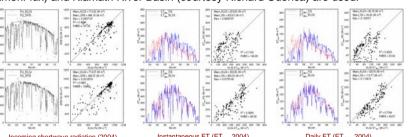
Key Features of the ET Estimation System

·Estimates actual ET and does not require ground weather observations

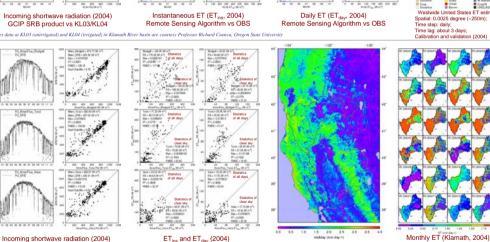
·Combines currently available remote sensing products (MODIS and NOAA SRB) and makes the process operational in near real-time.

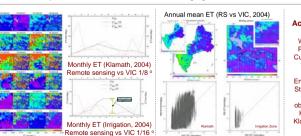
Implementation and Evaluation

Our study area is the western United States domain of (124.5W, 119.5W, 37.5N, 44N). Test tower flux sites at Blodgett Forest, Vaira Ranch and Tonzi Ranch (AmeriFlux) and Klamath River Basin (courtesy Richard Cuenca) are used.



Remote Sensing Algorithm vs AmeriFlux





GCIP SRB product vs AmeriFlux

Acknowledgement

We are grateful to Professor Richard Cuenca, Department of Biological & Ecological Engineering, Oregon State University who provided flux observations at sites KL03/KL04 in the Klamath River Basir



References Nishida, K., R. R. Nemani, S. W. Running, and J. M. Glassy (2003), An operational remote sensing algorithm of land of Developing Satellite-derived Estimates of Surface Moisture Status. J. Appl. Melecor., 32, 548–557. MODIS products: <a href="http://decideac.usgo: Simple hydrologically Based Model of Land Surface Water and Energy Fuzzes for GCML, J. Geophys. Res., 59(7)71, 144,74-428, 1994